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1. Overview

Thank you for purchasing the GL10-4PM local pulse positioning module developed and manufactured independently by Inovance.

This product is a 4-channel positioning output module used together with the H3U series PLC main module. It support 4-channel pulse output, with the highest output frequency of 200 kHz. Each channel contains 4 digital inputs, which can be used for positive and negative limit, home switch, and normal signal input.

This guide describes the specifications, characteristics and using methods of the product. Please read this guide carefully before using to ensure more safely usage. For how to use the user program development environment and how to design user programs, see the H3U Series PLC Instructions and Programming Guide (AM600 series main modules do not support this product). Visit our website (www.inovance.com) for the latest version of the guide.

2. Safety Information

Safety information and precautions are identified into two grades: Warning and Caution. Please make sure to operate properly with adequate safety assurance.

WARNING Indicates the improper operation which, if not avoided, may cause death or serious injury;

CAUTION indicates that failure to comply with the notice will result in minor or moderate personal injury or equipment damage.

In some cases, even failure to follow "Cautions" may also lead to serious consequences. Please make sure to follow both warnings and cautions, otherwise, it may cause death or serious injury, as well as product and relevant equipment and system damage.

Please keep this guide well so that it can be read when necessary and forward this guide to the end user.

During control system design

- WARNING**
 - Provide a safety circuit outside the PLC so that the control system can still work safely once external power failure or PLC fault occurs.
 - Add a fuse or circuit breaker because the module may smoke or catch fire due to long-time overcurrent caused by operation above rated current or load short-circuit.

- CAUTION**
 - An emergency stop circuit, a protection circuit, a forward/reverse operation interlocked circuit, and an upper position limit and lower position limit interlocked circuit must be set in the external circuits of PLC to prevent damage to the machine.
 - To ensure safe operation, for the output signals that may cause critical accidents, please design external protection circuit and safety mechanism;
 - Once PLC CPU detects abnormality in the system, all outputs may be closed; however, when a fault occurs in the controller circuit, the output may not be under control. Therefore, it is necessary to design an appropriate external control circuit to ensure normal operation;
 - If the PLC's output units such as relays or transistors are damaged, the output may fail to switch between ON and OFF states according to the commands;
 - The PLC is designed to be used in indoor electrical environment (overvoltage category II). The power supply must have a system-level lightning protection device, assuring that overvoltage due to lightning shock cannot be applied to the PLC's power supply input terminals, signal input terminals and output terminals and so forth, so as to avoid damage to the equipment.

During installation

- WARNING**
 - Installation must be carried out by the specialists who have received the necessary electrical training and understood enough electrical knowledge.
 - Disconnect all external power supplies of the system before removing/ installing the module. Failure to do so may result in electric shock, module fault or malfunction.
 - Do not use the PLC where there are dust, oil smoke, conductive dust, corrosive or combustible gases, or exposed to high temperature, condensation, wind & rain, or subject to vibration and impact. Electric shock, fire and malfunction may also result in damage or deterioration to the product.
 - The PLC is open-type equipment that must be installed in a control cabinet with lock (cabinet housing protection >IP20). Only the personnel who have received the necessary electrical training and understood enough electrical knowledge can open the cabinet.

- CAUTION**
 - Prevent metal filings and wire ends from dropping into ventilation holes of the PLC during installation. Failure to comply may result in fire, fault and malfunction.
 - Ensure there are no foreign matters on ventilation surface. Failure to comply may result in poor ventilation, which may cause fire, fault and malfunction.
 - Ensure the module is connected to the respective connector securely and hook the module firmly. Improper installation may result in malfunction, fault or fall-off.

During wiring

- WARNING**
 - Wiring must be carried out by personnel who have received the necessary electrical training and understood enough electrical knowledge.
 - Disconnect all external power supplies of the system before wiring. Failure to comply may result in electric shock, module fault or malfunction.
 - Install the terminal cover attached to the product before power-on or operation after wiring is completed. Failure to comply may result in electric shock
 - Perform good insulation on terminals so that insulation distance between cables will not reduce after cables are connected to terminals. Failure to comply may result in electric shock or damage to the equipment.

- CAUTION**
 - Prevent dropping metal filings and wire ends drop into ventilation holes of the PLC at wiring. Failure to comply may result in fire, fault and malfunction.
 - The external wiring specification and installation method must comply with local regulations. For details, see the wiring section in this guide.
 - To ensure safety of equipment and operator, use cables with sufficient diameter and connect the cables to ground reliably.
 - Wire the module correctly after making clear of the connector type. Failure to comply may result in module and external equipment fault.
 - Tighten bolts on the terminal block in the specified torque range. If the terminal is not tight, short-circuit, fire or malfunction may be caused. If the terminal is too tight, fall-off, short-circuit, fire or malfunction may be caused.
 - If the connector is used to connect with external equipment, perform correct crimping or welding with the tool specified by manufacturer. If connection is in poor contact, short-circuit, fire or malfunction may be caused.
 - A label on the top of the module is to prevent foreign matters entering the module. Do not remove the label during wiring. Remember to remove it before system operation, facilitating ventilation.
 - Do not bundle control wires, communication wires and power cables together. They must be run with distance of more than 100 mm. Otherwise, noise may result in malfunction.
 - Select shielded cable for high-frequency signal input/output in applications with serious interference so as to enhance system anti-interference ability.

During maintenance & inspection

- WARNING**
 - Maintenance & inspection must be carried out by personnel who have the necessary electrical training and experience.
 - Do not touch the terminals while the power is on. Failure to comply may result in electric shock or malfunction.
 - Disconnect all external power supplies of the system before cleaning the module or re-tightening screws on the terminal block or screws of the connector. Failure to comply may result in electric shock.
 - Disconnect all external power supplies of the system before removing the module or connecting/removing the communication wirings. Failure to comply may result in electric shock or malfunction.

- CAUTION**
 - Get with the guide and ensure safety before online modification, forcible output, and RUN/STOP operation.
 - Disconnect the power supply before installing/removing the extension card.

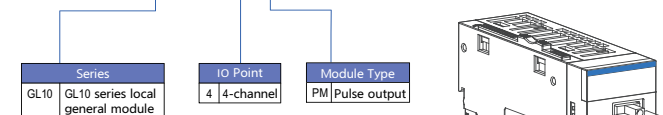
At disposal

- CAUTION**
 - Treat scrapped module as industrial waste. Dispose the battery according to local laws and regulations.

3. Product Information

Model and Nameplate

GL10-4PM



Nameplate

MODEL : GL10-4PM
 POWER INPUT : 24VDC 300mA
 OUTPUT : 24VDC 0.5A RES LOAD
 VER : xxxxx
 01022087YE400001
 01022087YE400001

Figure 1 Description of model and nameplate

Model	Classification	Description	Applicable Model
GL10-4PM	Local pulse positioning module	4-channel pulse positioning output	H3U series

External Interface

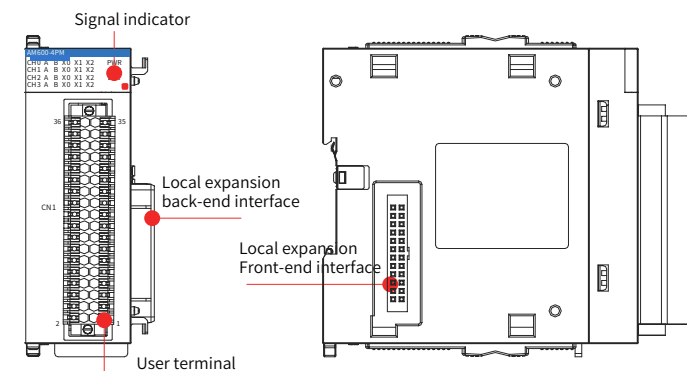


Figure 2 Module interfaces

Name	Function			
Signal indicator	PWR	Power indicator	Green	ON when power supply is switched on.
	RUN	Running status indicator	Green	ON when the module is in normal operation
	ERR	Error indicator	Red	Is ON after an error occurs
I/O signal indicator	For input and output signals ON: active OFF: inactive			
Local expansion module back-end interface	Connect back-end module, not supporting hot plugging			
Local expansion module front-end interface	Connects front-end module and does not support hot plugging			
Wiring terminal	4-channel pulse output terminal, see "Electrical Design Reference"			

Output specification

Item	Specifications
Output channels	4 (high-speed)
Output type	Transistor, SINK output
Power supply voltage	24 VDC (-15% to +20%)
Output voltage class	12 V to 24 V (-5% to 20%)
ON response time	1 us (hardware response time)
OFF response time	1 us (hardware response time)
Output frequency	200 kHz (external equivalent load of 20 mA or more is required when output is above 50 kHz)
Maximum load current	0.5 A/point
Isolation mode	Opto-couplers isolation

Input specification

Item	Specifications
Input channels	16
Input type	Supports SINK and SOURCE input
Input voltage	24 VDC (-15% to +20%)
ON current	More than 3.5 mA
OFF current	Less than 1.5 mA
Input resistance	3.3 KΩ
Isolation method	Opto-couplers isolation

4. Mechanical Design Reference

Mounting Dimensions

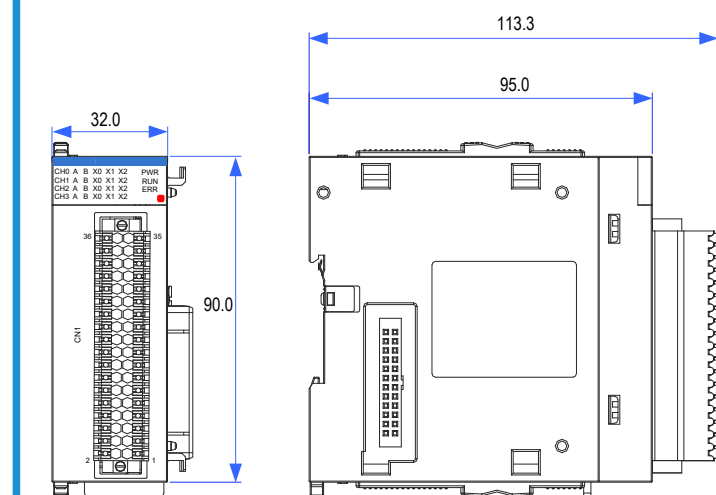


Figure 3 Installation dimensions (mm)

5. Electrical Design Reference

Cable Selection

Cable Name	Model	Applicable Cable Diameter		Manufacturer	Crimping Tool
		Chinese Standard/MM	AWG		
Tubular lug	GTVE07512	0.75	21	Suzhou Yuanli	YAC-5

Cable Preparing Procedures

- Remove the insulation of the cable so that a length of 11-14 mm of the conductor is exposed, and put the cable through a cable marking sleeve.
- Insert the exposed end into the hole of the cable lug, and then crimp it with

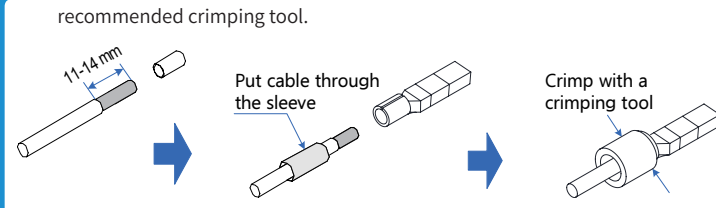


Figure 4 Diagram of cable preparing

Terminal Arrangement

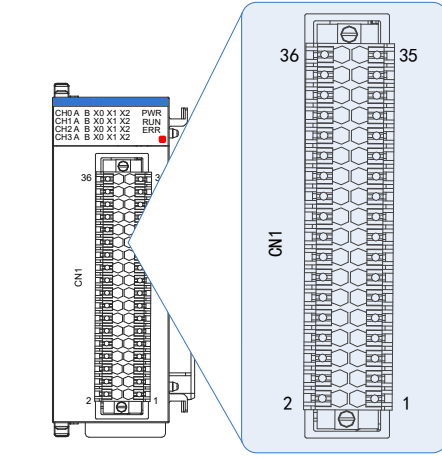
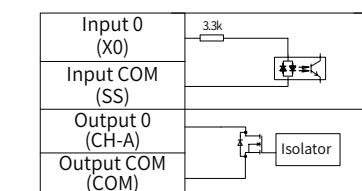


Figure 5 Terminal definition of the module

External Wiring

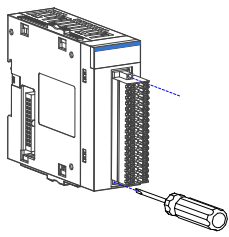
Ext. Wiring	Signal Name	Terminal No.	Signal Name	Ext. Wiring	
	Column B		Column A		
24VDC	CH1 POS limit (CH1-X0)	36	CH0 POS limit (CH0-X0)	24VDC	
	CH1 NEG limit (CH1-X1)	34	CH0 NEG limit (CH0-X1)		
	CH1 HOME switch (CH1-X2)	32	CH0 HOME switch (CH0-X2)		
	CH1 normal input (CH1-X3)	30	CH0 normal input (CH0-X3)		
	CH1 normal input COM (SS0)	28	CH0 normal input COM (SS0)		
	CH3 POS limit (CH3-X0)	26	CH2 POS limit (CH2-X0)		
	CH3 NEG limit (CH3-X1)	24	CH2 NEG limit (CH2-X1)		
	CH3 HOME switch (CH3-X2)	22	CH2 HOME switch (CH2-X2)		
	CH3 normal input (CH3-X3)	20	CH2 normal input (CH2-X3)		
	CH3 input COM (SS1)	18	CH2 input COM (SS1)		
	(Vacant)	16	(Vacant)		
	CH1 output A (CH1-A)	14	CH0 output A (CH0-A)		Load
	CH1 output B (CH1-B)	12	CH0 output B (CH0-B)		
	CH3 output A (CH3-A)	10	CH2 output A (CH2-A)		
	CH3 output B (CH3-B)	8	CH2 output B (CH2-B)		
	output COM (COM)	6	output COM (COM)		
24 V power + (24V)	4	24 V power - (GND)			
24 V power + (24V)	2	24 V power - (GND)	24VDC		

internal equivalent circuit



Precautions

After the IO terminal block is mounted to CN1, fix it with a torque of 0.2–0.25 N m, as shown in the figure.

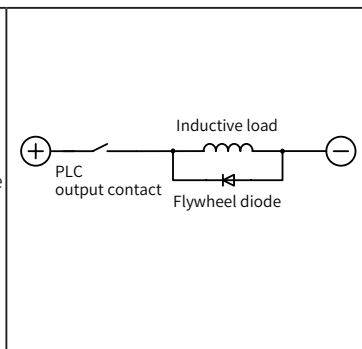


Do not bundle the terminal connection cables together with power cables (high voltage, large current) which produce strong interference signals. Separate it from other cables and avoid cabling in parallel.

Use recommended cables and adapter boards. It is recommended to use shielded cables as terminal cables for increased anti-interference ability.

Contact protection in the case of inductive load

When the inductive load is applied, large back EMF will be produced between contacts and arc discharge is also caused when the inductive load stops. This may result in contact failure or contact sag, shortening the contact lifetime. Therefore, you can use a parallel flywheel diode with the load to extend the lifetime of the product. The freewheel diode must satisfy: ① reverse voltage is 5 to 10 times of load voltage; ② forward current is larger than load current.

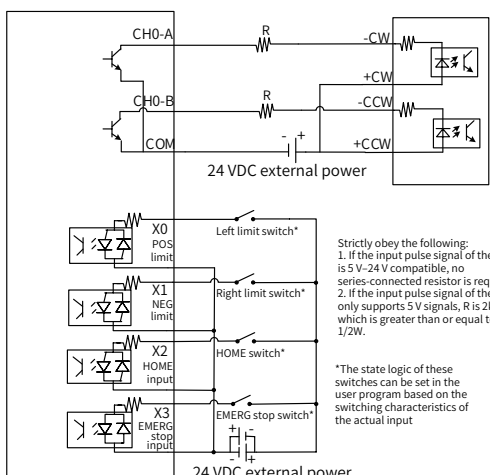


Wiring

This module supports CW/CCW and pulse+direction pulse output, and the wiring is as follows.

Pulse output mode 1: CW/CCW

GL10-4PM

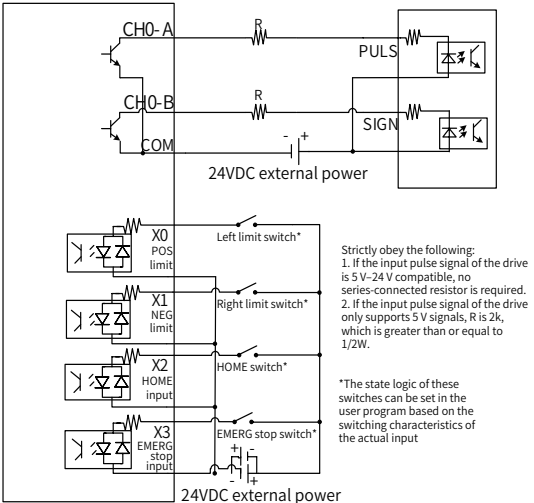


Strictly obey the following: 1. If the input pulse signal of the drive is 5V~24V compatible, no series-connected resistor is required. 2. If the input pulse signal of the drive only supports 5V signals, R is 2k, which is greater than or equal to 1/2W.

*The state logic of these switches can be set in the user program based on the switching characteristics of the actual input

Pulse output mode 2: pulse+direction

GL10-4PM



Strictly obey the following: 1. If the input pulse signal of the drive is 5V~24V compatible, no series-connected resistor is required. 2. If the input pulse signal of the drive only supports 5V signals, R is 2k, which is greater than or equal to 1/2W.

*The state logic of these switches can be set in the user program based on the switching characteristics of the actual input

NOTE During wiring, follow the specifications of the corresponding servo drive or stepper motor drive.

6. Programming Reference

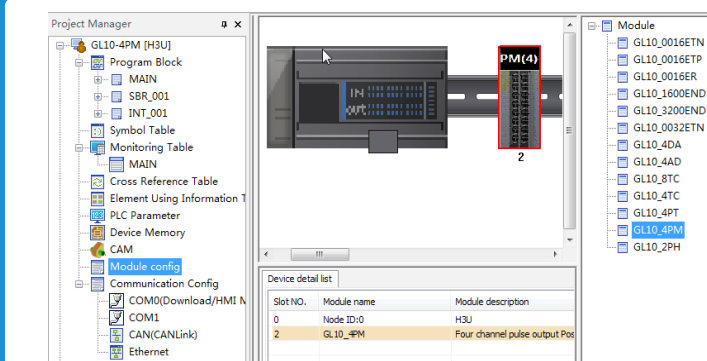
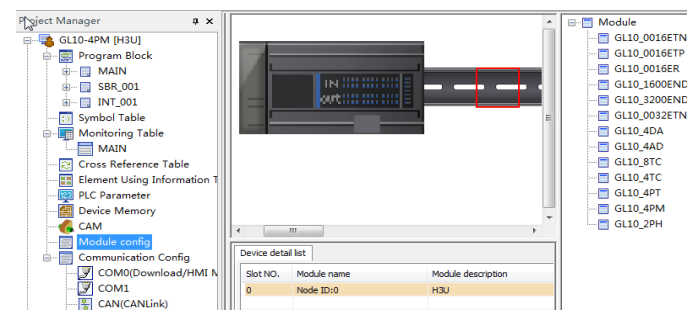
Supported H3U Instructions

Table with 7 columns: Instruction, S1, S2, S3, S4, D1, D2. Rows include PMDRVA, PMDRVI, PMPLSV2, PMHOME, PMSETPOS, PMSTOP, PMWRPARA, and Write special parameters.

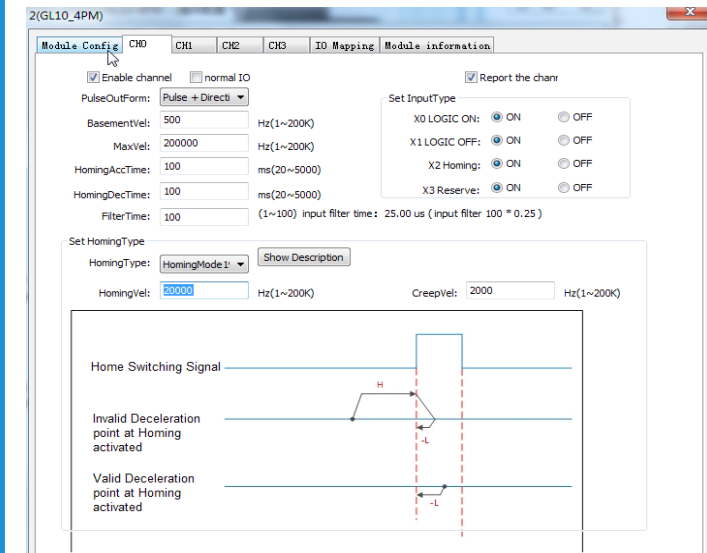
Programming example:

In the following example, this module is used with the H3U series main module to realize the following function: the relative positioning instruction is called to send 10000 pulses in the mode of pulse+direction through channel CH0 with a frequency of 10 KHz. The acceleration time is 100 ms and the deceleration time is 100 ms.

- 1) Start AutoShop, select Module Configuration, and then select the GL10-4PM module and drag it to the red block.



2) Double-click the GL10-4PM module in the figure to configure it. Select the channel to be used. As shown in the figure below, the configuration window provides detailed settings including the pulse output mode, input signal positive and negative logic, and speed parameters for each output channel:



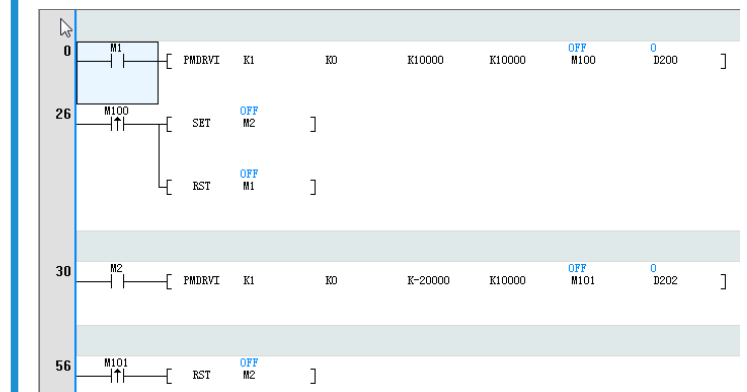
- ◆ Enable channel: Check to use the current channel.
◆ Pulse output mode: Two modes are available: CW/CCW and pulse+direction.
◆ Base speed: limits the minimum speed of the pulse module.
◆ Maximum speed: limits the maximum pulse output frequency of the current module.
◆ Acceleration time: the pre-set time for the base speed to reach the target speed, in ms.
◆ Deceleration time: the pre-set time for the target speed to decelerate to the base speed, in ms.
◆ Homing: 4 homing modes are available. The user can input positive limit, negative limit, homing and other signals according to the actual mechanical structure to achieve expected homing.
◆ Homing speed: the set value of high-speed homing speed.
◆ Approaching speed: the set speed to approach the target position.
◆ Input filtering: reduces interference with signals such as positive limit, negative limit, and homing.
◆ Input signal logic: Configure according to the contactor type of the input terminal. The NO contact is defined as positive logic and the NC contact is defined as negative logic.
3) After configuring the channel parameters according to the actual application scenario, select I/O mapping to map the D component and R component to the corresponding channel position and state.

Table with 3 columns: Channel map element, Channel, Type. Lists channels D1000 through D1010 and their corresponding states and bit widths.

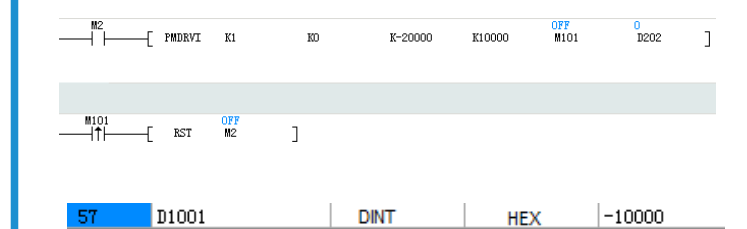
The data of each channel position is a 32-bit signed integer, and the channel state is 16-bit (as shown in the figure above, D1000 is mapped to the current state of CH0, D1003 to CH1, and so on). The meaning of each bit is as shown in the following table [data format: BOOL-(1bit)].

Table with 4 columns: Bit, Buff Definition, Bit, Buff Definition. Maps bits 0-15 to various channel states like pulse output completion, acceleration, and limit signals.

4) PLC programming



- ◆ PMDRVI relative positioning, module No.: 1, channel: CH0, pulses: 10000, target speed: 10000 Hz, error flag: D200, positioning completion flag: M100.
◆ Enable M1. After 10000 pulses are output, M100 turns ON, which means the instruction is executed. The position of CH0 is 10000. At this time, M1 will be reset and M2 will be set, which enables the next relative positioning instruction, with the number of pulses being -20000, the target speed being 10000 Hz, the error flag being D202, and the positioning completion flag being M101.



7. Fault Code and Solutions

By checking Bit12–Bit15 of the channel mapping component (for the mapping component set by the user in the module configuration, see step 3 of Programming Examples above), you can determine the module error type; you can also check the error code information of the PLC program through the software tool to determine the host error type or module error type.

Table with 3 columns: Item, Error Code, Description. Lists error codes 1 through 1199 and their corresponding descriptions, categorized into Module reported errors and Host reported error.

INOVANCE Warranty Agreement

- 1) Inovance provides an 18-month free warranty to the equipment itself from the date of manufacturing for the failure or damage under normal use conditions.
2) Within the warranty period, maintenance will be charged for the damage caused by the following reasons:
a. Improper use or repair/modification without prior permission
b. Fire, flood, abnormal voltage, natural disasters and secondary disasters
c. Hardware damage caused by dropping or transportation after procurement
d. Operations not following the user instructions
e. Damage out of the equipment (for example, external device factors)
3) The maintenance fee is charged according to the latest Maintenance Price List of Inovance.
4) If there is any problem during the service, contact Inovance's agent or Inovance directly.
5) Inovance reserves the rights for explanation of this agreement.

Suzhou Inovance Technology Co., Ltd.

Address: No.16, Youxiang Road, Yuexi Town, Wuzhong District, Suzhou 215104, P.R. China

Website: http://www.inovance.com